# **PHI** A Modern C++ Library for Parallel Pattern Composition

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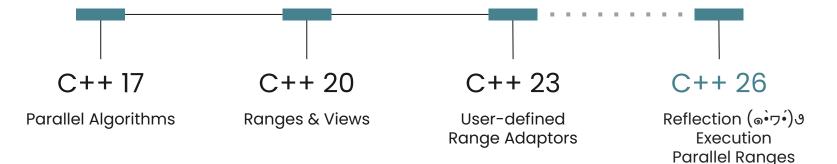
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#### Introduction



- Programming languages evolve, so does the way to express code.
- Pattern-based programming improves readability and maintainability.
- Ranges enable more expressive, composable, and safer code.
- Transition from iterators to ranges.
- Parallel code can benefit from similar abstractions.



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### C++ 20 Ranges | Background



- High-level abstraction that supersedes iterators.
  - Introduces the concepts of ranges & views.
- Replaces the use of iterator-pairs with a pipe-like syntax.
- Generally lazily evaluated.

```
0 // View Composition
1 auto && squares = std::views::iota(1) // Infinite Range [1 ... N]
2 | std::views::transform([] (int x) { return x * x; }) // Square elements
3 | std::views::filter([] (int x) { return x > 100; }) // Keep elements > 100
4 | std::views::take(10) // Keep 10 elements
5 ;
6 // View Evaluation (Print Elements)
7 for (auto element: squares) std::print("{} ", element);
8 // Another Evaluation (Print Average)
9 std::print("[{}]", std::ranges::fold_left(squares, 0.0, std::plus{}) / 10.0);
```



https://godbolt.org/z/ehvlEfsze

#### Parallel Patterns | Background

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- Programming patterns are widely recognized as a best practice.
- They define a clear mapping between input and output data, using a transformation function to express the computation to be done in parallel
- Parallel control patterns (data parallel patterns)
  - Map, reduce, stencil
- Parallel data management patterns
  - Pipeline, pack/unpack, scatter/gather



- Commonly found in OpenMP.
- Primarily based on pragma directives.
- Requires minimal code changes.
- Limited type support.
- Obscure error messages.

#### Macros

```
void openmp(float a[], float b[], int n) {
    int i, j;
1
    #pragma omp parallel shared(a,b,n)
2
3
    {
     #pragma omp for schedule(dynamic,1) private (i,j) nowait
4
     for (i = 1; i < n; i++)</pre>
5
         for (j = 0; j < i; j++)</pre>
6
           b[j + n*i] = (a[j + n*i] + a[j + n*(i-1)]) / 2.0;
7
    }
8
9 }
```



- No method chaining.
- Often stateless and reusable.
- Could be composable but not "fluent".
- Most common among parallel frameworks and libraries.

#### **Free Functions**

```
0 // Intel TBB
1 tbb::parallel_for(0, static_cast<int>(v1.size()), [&](int i) {
2  v1[i] = i * i;
3 });
```

```
0 // C++17 Parallel Algorithms
1 std::for_each(std::execution::parallel_policy{},
2 v1.begin(), v1.end(),
3 [] (int &x) { x = x*2; }
4 );
0 // GrPPI
```

```
1 grppi::map(grppi:: parallel_execution_native{}, v1, v1,
2 [](int &x) { x = x * 2; }
```

```
3);
```



- Declarative, functional style.
- Chainable operations.
- Returns \*this or new object for chaining.
- Similar to range-like pipes.

#### Fluent / Chaining Style

#### 0 // RxCPP

- 1 auto values = rxcpp::observable⇔::range(1, 10)
- 2 .map([](int v) { return v \* 2; })
- 3 .filter([](int v) { return v % 2 = 0; })
- 4 .reduce(0, [](int acc, int v) { return acc + v; });



- Heterogenous frameworks
  - SYCL Ο
  - CUDA Ο
  - OpenCL Ο
- Work-items and work-groups
- Manual index calculation
- Direct memory access

```
// SYCL 2020
0
```

```
1 q.submit([&](sycl::handler& h) {
    auto in = in_buf.get_access<sycl::access::mode::read>(h);
2
    auto out = out_buf.get_access<sycl::access::mode::write>(h);
3
4
```

Kernel

```
h.parallel_for(sycl::range<1>{N}, [=](sycl::id<1> i) {
```

```
out[i] = in[i] * in[i];
```

```
});
6
```

5

```
7 });
```

```
0 // CUDA
1 __global__ void square_kernel(int* input, int* output, int N) {
    int i = blockIdx.x * blockDim.x + threadIdx.x;
2
    if(i < N)
3
4
      output[i] = input[i] * input[i];
5 }
```

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#### Interface | Design

- PHI builds on the foundations and concepts of GrPPI.
- PHI's core abstractions:
  - Range adaptors.
  - Data-parallel patterns.
  - Execution backends.
- Pattern composition & execution should be decoupled.
- Parallel Patterns are modeled after Range Adaptors.
- Avoid explicitly composed patterns like map-reduce.
- Type constraints.



#### https://github.com/arcosuc3m/grppi



## Range Adaptors | Design

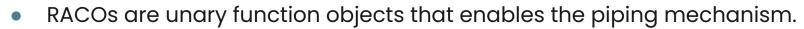


- Range Adaptors are Customization Point Objects (CPOs) that transform a range into another range-like object.
- They create deeply nested types.

```
0 // Using pipe syntax
1 auto && view = range | adaptor_1 | adaptor_2;
2 // Equivalent without RACOs
3 auto && view = adaptor_2(adaptor_1(range));
```

```
0 // std::ranges::views::__adaptor::_Partial<std::views::_Transform, lambda(int)>
1 auto && T = std::views::transform([] (int x) {return x;});
2
3 // std::ranges::transform_view<std::ranges::iota_view<int, std::unreachable_sentinel_t>, lambda(int)>
4 auto && I = std::views::iota(1) | T;
```

#### Range Adaptor Closures | Design



- When applied to a range: the output is a view.
- When applied to a RACO: the output is a closure object.

```
@ struct identity_fn : std::ranges::range_adaptor_closure<identity_fn> {
     template<std::ranges::viewable_range Rng>
 1
     constexpr auto operator()(Rng && range) const {
 2
 3
       return std::forward<Rng>(range);
 4
     }
 5 };
 6 inline constexpr auto identity = identity_fn{};
 7
   // Usage Example
9 int main() {
     for (auto x : std::vector{1,2,3,4} | identity)
10
       std::print("{} ", x); // Prints 1 2 3 4
11
12 }
```



https://godbolt.org/z/835GhMaE8

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## Map Adaptors | Design



- Modeled after Unary functions.
- N-ary interface substituted by zip views over data.
- Unary Transformer: **U res = op(x)**
- Transformer function must be pure.

```
// Illustrative Interface - Unary Map Transformer
0
1 auto transformer = [] (T element) \rightarrow U
      { return /* Transformation Op */ ; };
2
3
  // Usage Example
4
  auto pipeline = input_range<T>
5
      | phi::map(transformer)
6
      | phi::map([ ] (U element) { return 42 * element; })
7
8
      ;
```

#### Reduce Adaptors | Design



- Modeled after a combiner function & identity value.
- Combiner: T res = cmb(T x, U y).
- Combiner function should be pure & associative.
- Special type of adaptor  $\rightarrow$  "Terminal Operation / Range"

```
0 // Illustrative Interface - Reduce Combiner
1 auto combiner = [] (T element_1, U element_2) → T
2 { return /* Combination Op */; };
3
4 // Usage Example
5 auto pipeline = input_range<T>
6 | phi::map([] (T e) → T { return e * e; } )
7 | phi::reduce([] (T e1, U e2) { return e1 + e2; } , 0) // Identity Value
8 // | phi::reduce(std::plus{}, 0) // Equivalent Expression
9 ;
```

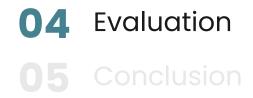
## Type Requirements | Design



- Performance impact & implementation challenges
  - Irregularly structured data in memory.
  - Data that cannot be partitioned into parallel units.
- C++ Proposal P3179 authors' identify random access iterators as a common requirement across many existing parallel execution models.
- Ranges must be bounded in size.
  - std::ranges::iota\_view produces unbounded sequences.

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- Embarrassingly parallel escape-time algorithm.
- Well-suited for map-pattern decomposition.
- The algorithm has these stages:
  - Initialization of a grid of data points.
  - Mapping each grid index to a corresponding coordinate in the complex plane.
  - Running the escape-time iteration for each complex point.

```
0 // Precompute the change in real and imaginary components (x_step, y_step)
 1 double const x_step = (plane.x_max - plane.x_min) / image_width;
 2 double const y_step = (plane.y_max - plane.y_min) / image_height;
     Initialize the matrix (std::vector<unsigned>) from 0 to N
 5 std::ranges::iota(matrix, 0);
      Execution loop
 8 for (unsigned const n : matrix) {
     // Convert 1D index to 2D index (i, j)
 9
     unsigned x = n % matrix.width;
10
     unsigned y = n / matrix.width;
11
12
     // Map index to complex plane coordinates (x, y)
13
     double real = plane.x_min + (x * x_step);
14
     double imag = plane.y_min + (y * y_step);
15
16
17
     // Compute escape time for the complex point
     std::complex<double> c(real, imag);
18
19
     std::complex<double> z(0.0, 0.0);
```

```
20 unsigned iterations = 0;
```

```
21 while (std::norm(z) \leq escape_value * 2 & iterations < max_iterations) {
```

```
22 z = std::pow(z, 2) + c;
```

```
23 ++iterations;
```

```
24
```

```
25 output[n] = iterations; // Assume that output is correctly sized
```

#### **Traditional Algorithm**

- All stages of the computation are embedded directly in the inner loop.
- Executed eagerly at each iteration
- Algorithm and implementation details are coupled.
- More complex algorithms could introduce errors with indexed array accesses.

```
0 // Precompute the change in real and imaginary components (x_step, y_step)
1 // x_min, x_max, y_min, and y_max represent a window in the complex plane
2 double const x_step{(plane.x_max - plane.x_min) / image_width};
3 double const y_step{(plane.y_max - plane.y_min) / image_height};
4
5 // Initialize the matrix (std::vector<unsigned>) from 0 to N
```

```
6 std::ranges::iota(matrix, 0);
```

```
8 // Transform iota value (n) to an idx value (i, j) \rightarrow 1D index to 2D index
9 auto iota_to_idx = [&] (unsigned const value) \rightarrow coordinates<unsigned> {
     return {.x = value % matrix.width, .y = value / matrix.width};
10
11 };
12
13 //
      Transform the idx pair to a coordinate pair belonging to the Mandelbrot set
14 auto idx_to_xy = [=] (coordinates<unsigned> const & ij)
       → coordinates<double> {
     return {.x = x_min + (ij.x * x_step), .y = y_min + (ij.y * y_step)};
16
17 };
18
      Compute escape time for the complex point
19 //
20 auto xy_to_escape = [=] (coordinates<double> const & xy) \rightarrow unsigned {
     unsigned iterations{0};
21
     std::complex const c{xy.x, xy.y};
22
     std::complex<double> z{0, 0};
23
```

```
24 while (std::norm(z) \leq escape_value * 2 && iterations < max_iterations) {
```

```
25 z = pow(z, 2) + c;
```

```
6 ++iterations;
```

```
27 }
```

```
28 return iterations;
```

```
29 };
```

#### Lambda Algorithmic Skeleton

- Loop has been replaced with lambdas representing data transformations.
  - A single lambda would've sufficed.
- Less intuitive than the iterative version, but easier to compose, reuse, and abstract.
- None of the lambdas are eagerly executed.

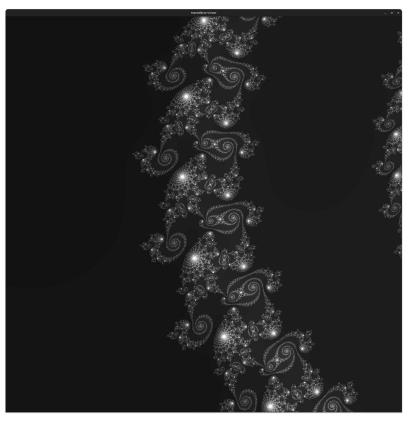
- Each lambda can now be composed into declarative pipelines.
- Lambdas can be re-used with minimal assumptions about the underlying data range.
- The pipeline can be executed iteratively as a range-loop; or passed to an offloading backend.

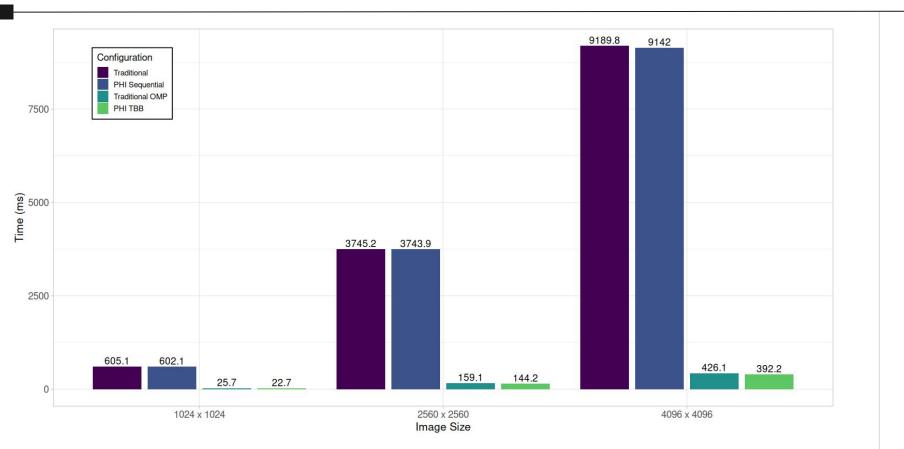
0	<pre>// Pattern composition</pre>
1	auto && pipeline =
2	matrix
3	phi::map(iota_to_idx)
4	phi::map(idx_to_xy)
5	phi::map(xy_to_escape)
6	;
7	
8	<pre>// Pipeline execution</pre>
9	<pre>phi::execute(pipeline, output);</pre>





Machine Configuration			
CPU (X86_64)	AMD Ryzen 9 5950X		
Cores	16 (2 threads per core)		
Base - Max Frequency	2200 MHz - 5083 MHz		
L1 Cache	512 KiB + 512 KiB		
L2 Cache	8 MiB		
L3 Cache	64 MiB (2x)		
Compilation Configuration			
Compiler	GCC 14.2.0		
Compiler Flags	GCC 14.2.0 -O3 -DNDEBUG		
-	-O3 -DNDEBUG		
Flags	-O3 -DNDEBUG		
Flags Mandelbrot C	-O3 -DNDEBUG		





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#### Conclusion



- PHI leverages more idiomatic C++ range-like interfaces.
- Range adaptors and closure objects are the foundation of function composition for lazy evaluation.
- PHI is in early stages of development. Improvements need to be made.
  - More pattern adaptors: **stencil scan filter zip**.
  - Support for in-place data. Requires careful study.
  - Improved support for backend integration, and more backends.
    - Deeply nested types are difficult to work with. Study a better representation.
  - Non-linear chains of transformation.
  - Additional and more complex use-cases.

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